

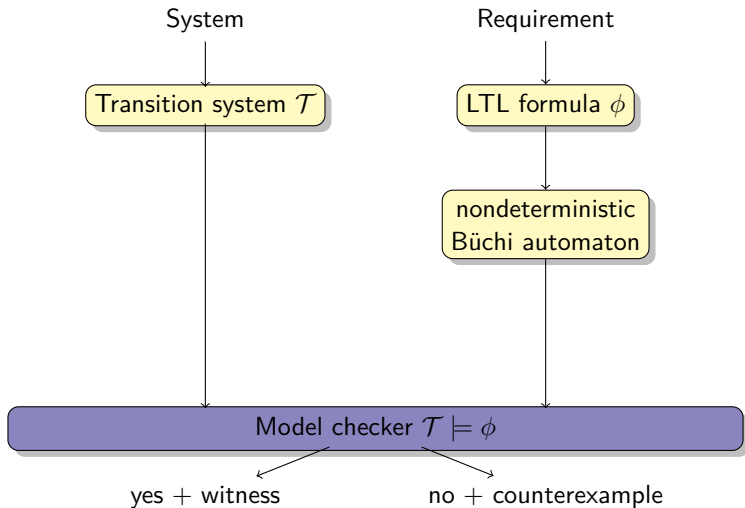
Are Good-for-games Automata Good for Probabilistic Model Checking?

Joachim Klein, **David Müller**, Christel Baier, Sascha Klüppelholz

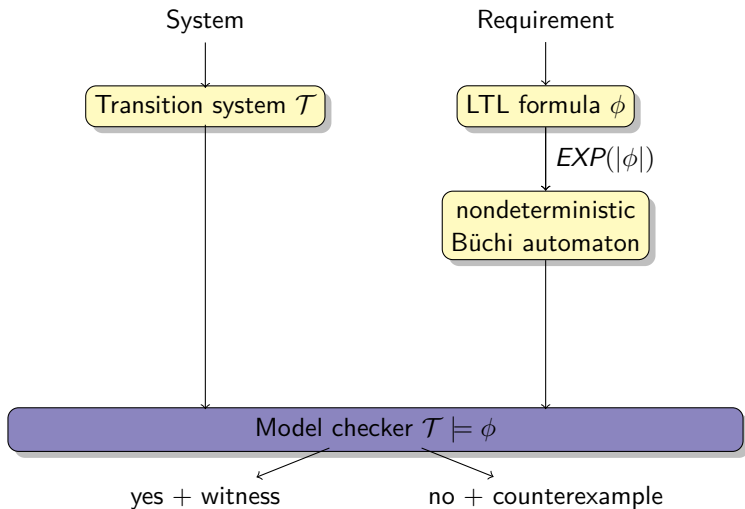
Institute for Theoretical Computer Science
Technische Universität Dresden

March 15, 2014

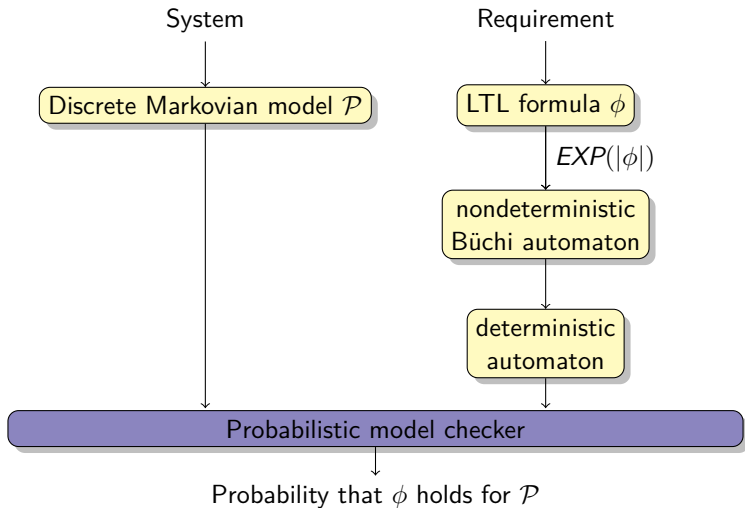
LTL model checking



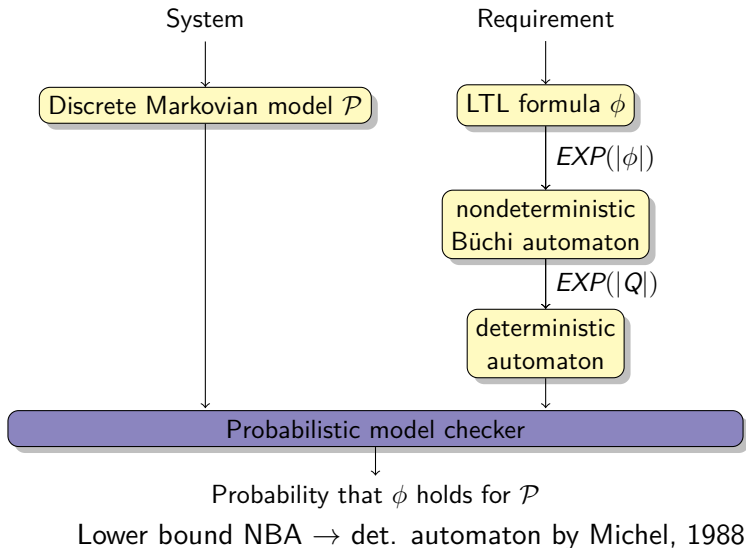
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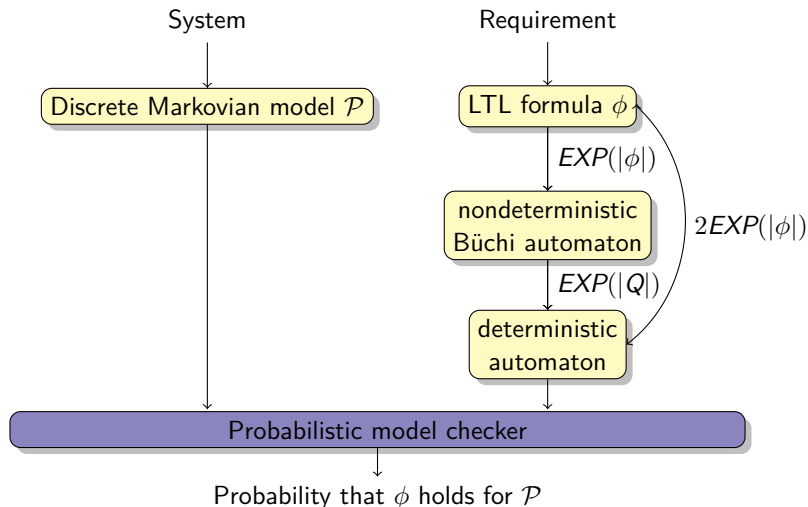
Probabilistic model checking



Probabilistic model checking



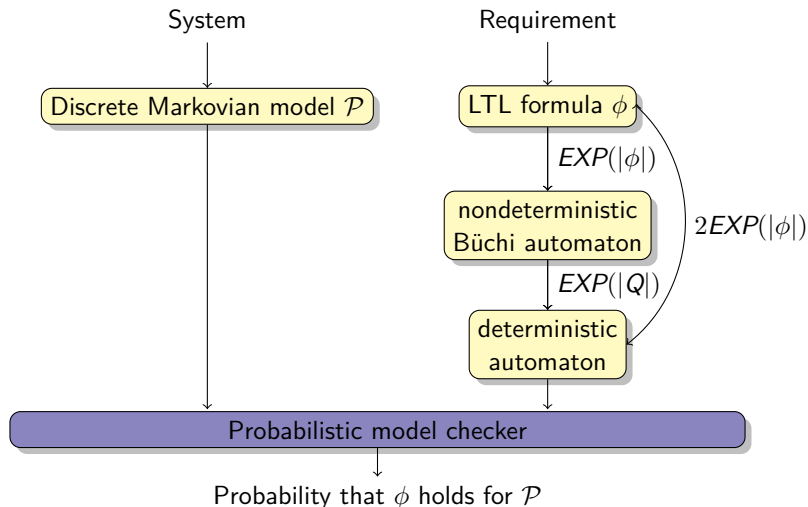
Probabilistic model checking



Lower bound NBA \rightarrow det. automaton by Michel, 1988

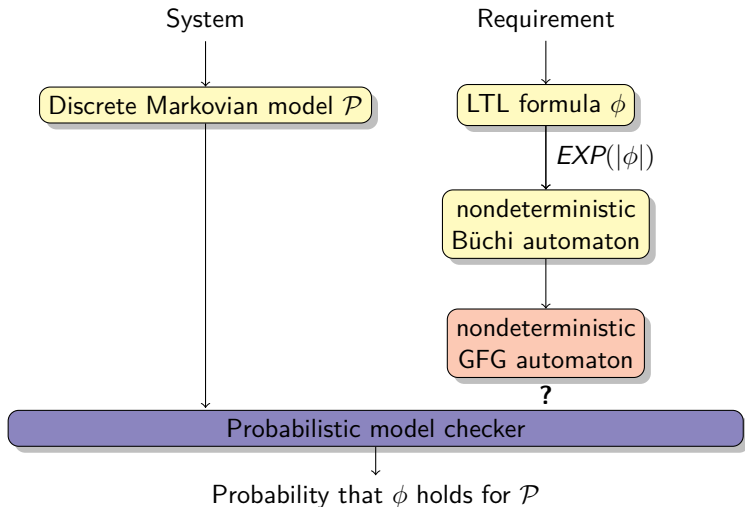
Lower bound LTL \rightarrow det. automaton by Kupferman, Rosenberg, 2011

Probabilistic model checking



For MDP \mathcal{P} and LTL ϕ $Pr_{\mathcal{P}}^{max}(\phi)$ is 2EXPTIME-complete by Courcoubetis, Yannakakis, 1995

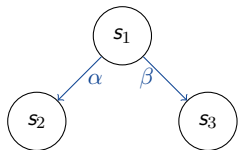
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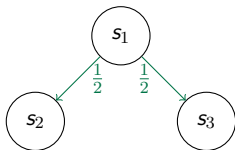
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- 1 Introduction
- 2 GFG-based analysis of MDPs
- 3 Evaluation
- 4 Conclusion

MDP: Probabilism and nondeterminism

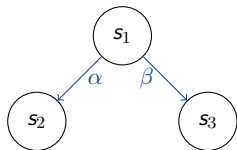


Transition system:
Nondeterminism

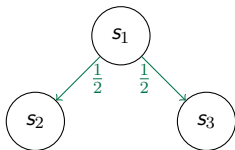


Markov chain:
Probabilism

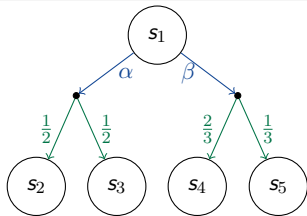
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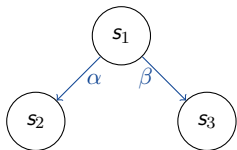


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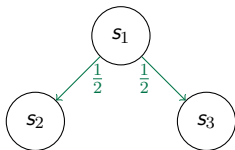


Markov decision
process:
Nondeterminism and
probabilism

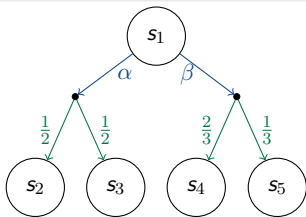
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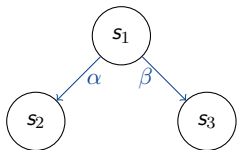
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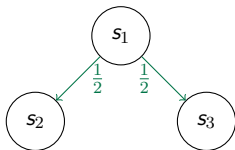
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Scheduler $\mathcal{G} : S^+ \rightarrow Act$ chooses
for given history of states next action

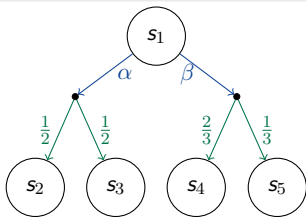
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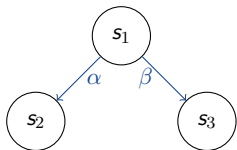


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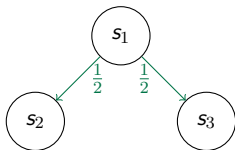
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$Pr_{\mathcal{P}}(\diamond s_4) ?$

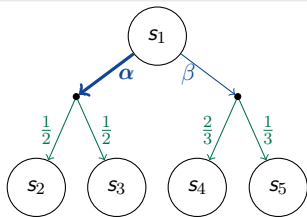
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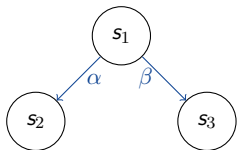


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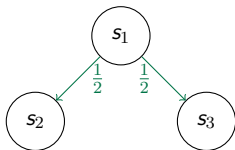
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$$Pr_{\mathcal{P}}(\diamond s_4) ? \longrightarrow Pr_{\mathcal{P}}^{\min}(\diamond s_4) = 0$$

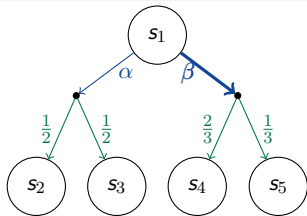
MDP: Probabilism and nondeterminism



Transition system:
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Markov decision
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Scheduler $\mathcal{S} : S^+ \rightarrow Act$ chooses
for given history of states next action

$$Pr_{\mathcal{P}}(\diamond s_4) ? \begin{cases} \rightarrow Pr_{\mathcal{P}}^{max}(\diamond s_4) = \frac{2}{3} \\ \rightarrow Pr_{\mathcal{P}}^{min}(\diamond s_4) = 0 \end{cases}$$

Good-for-games automata

- Property of nondeterministic automata

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- defined in Henzinger, Piterman, 2006 “Solving games without determinization”

Good-for-games automata

- Property of nondeterministic automata
- defined in Henzinger, Piterman, 2006 “Solving games without determinization”
- Used to avoid determinisation for LTL synthesis

Good-for-games automata

deterministic automata

$w \in \mathcal{L}(\mathcal{A}) \Leftrightarrow$ *unique run is an accepting run*

Nondeterministic automata

$w \in \mathcal{L}(\mathcal{A}) \Leftrightarrow$ *exists an accepting run*

Good-for-games automata

deterministic automata

$w \in \mathcal{L}(\mathcal{A}) \Leftrightarrow$ *unique run is an accepting run*

Good-for-games

exists a strategy s.t.

for all $w \in \mathcal{L}(\mathcal{A})$ strategy-induced run accepting

Nondeterministic automata

$w \in \mathcal{L}(\mathcal{A}) \Leftrightarrow$ *exists an accepting run*

Good-for-games

- two player game on the automaton:

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Definition

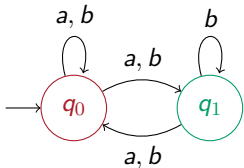
An ω -automaton is *good-for-games* if there exists a strategy, s.t. for every word $w \in \mathcal{L}(\mathcal{A})$ the induced run is accepting.

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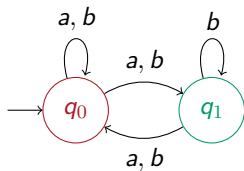


$$Acc = \diamond \square \neg q_0 \wedge \square \diamond q_1$$

Run π is accepting $\Leftrightarrow q_0 \notin \text{inf}(\pi) \wedge q_1 \in \text{inf}(\pi)$

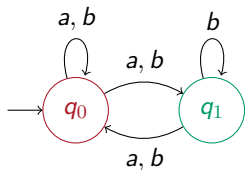
$$\mathcal{L}(\mathcal{A}) = \mathcal{L}((a + b)^* b^\omega)$$

Strategy



$$D(\pi) = \begin{cases} \text{GFG strategy} \\ q_0 & \text{if } \pi \text{ ends with } q_1 a \\ q_1 & \text{otherwise} \end{cases}$$

Strategy

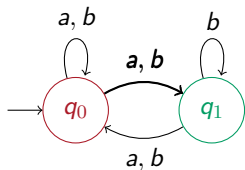


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The word $abab^\omega$ induces the following play:

word	a
play	$q_0 a$

Strategy

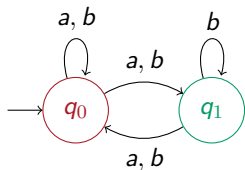


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Strategy

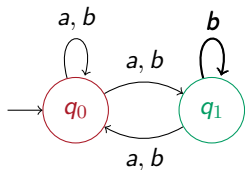


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word	a	b
play	$q_0 a$	$q_1 b$

Strategy

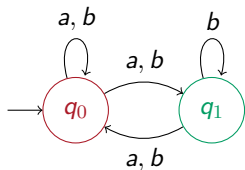


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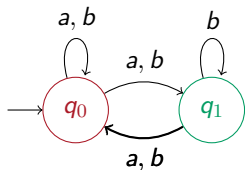


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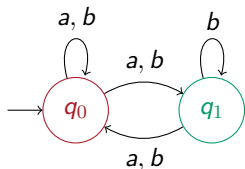


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Strategy

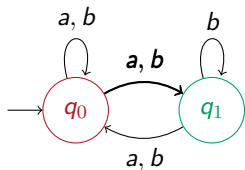


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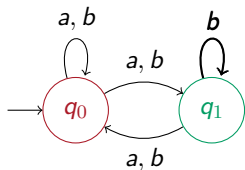


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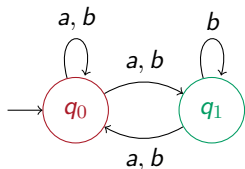


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word	a	b	a	b^ω
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Strategy



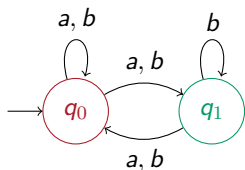
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Strategy



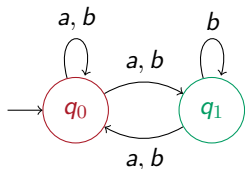
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- Every induced D -run remains in q_1 from some point on

Strategy



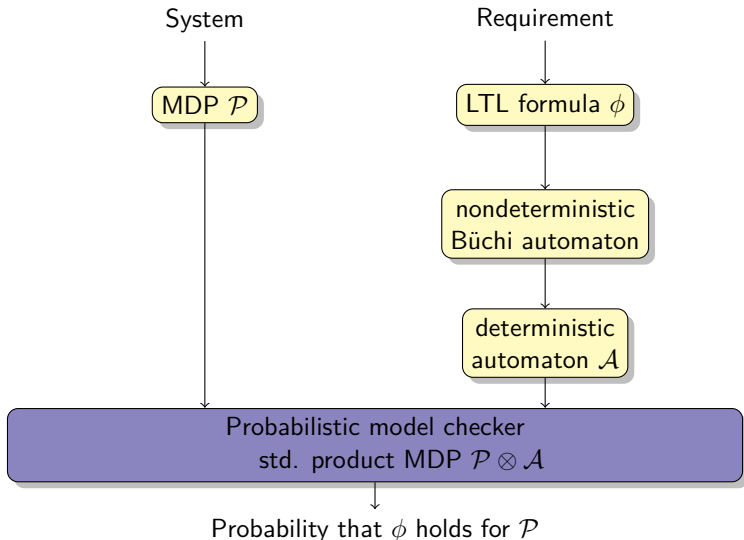
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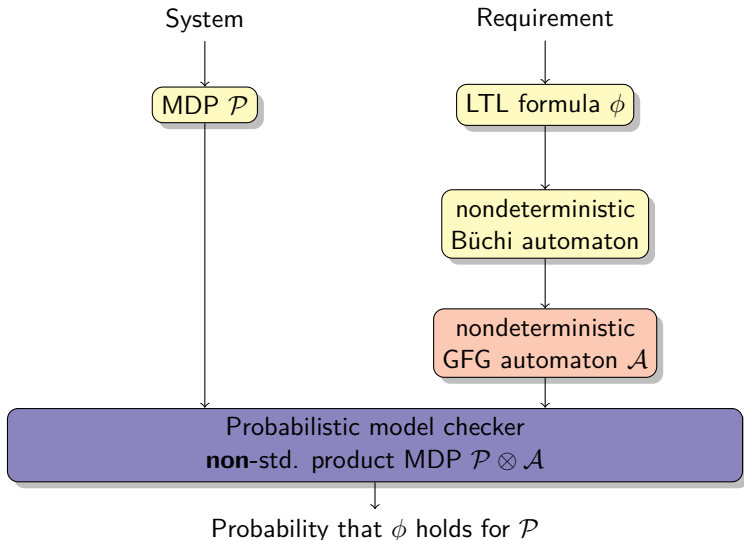
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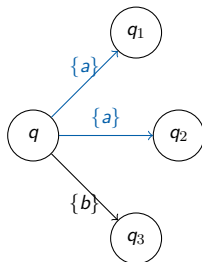
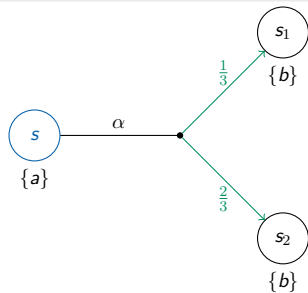
- For an accepted word player 1 has to choose b from some point on
- Every induced D -run remains in q_1 from some point on
- Every induced D -run is accepting

Probabilistic model checking

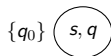


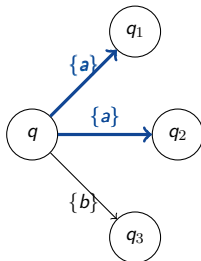
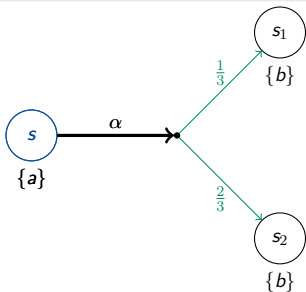
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Product MDP: $\mathcal{P} \otimes \mathcal{A}$ 

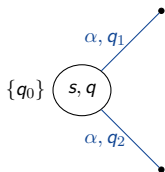
For state (s, q) in $\mathcal{P} \otimes \mathcal{A}$:

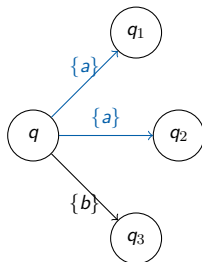
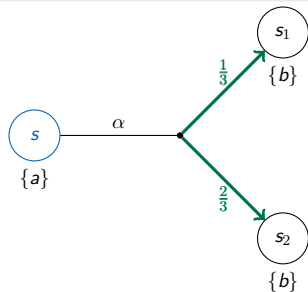


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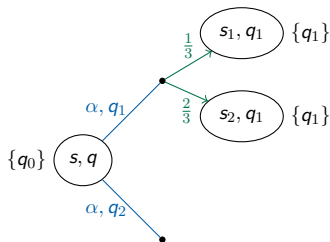
- enabled actions: (α, q') for $\alpha \in Act(s)$ and $q' \in \delta(q, L(s))$

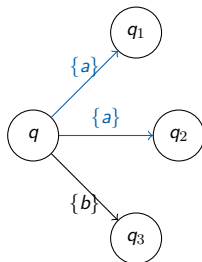
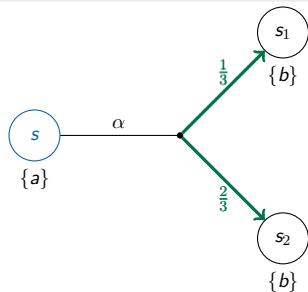


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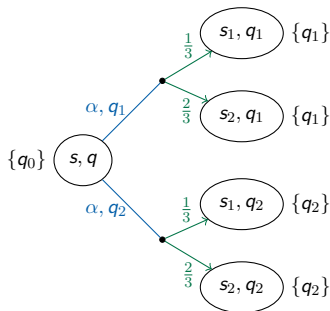
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- If action α, q' chosen, take over probability distributions of s in \mathcal{P}



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MDP analysis with GFG

Theorem

Let \mathcal{P} be an MDP and \mathcal{A} be an GFG ω -automaton. Then

$$Pr_{\mathcal{P} \otimes \mathcal{A}}^{\max}(\langle s_0, q_0 \rangle \models Acc) = Pr_{\mathcal{P}}^{\max}(s_0 \models \mathcal{L}(\mathcal{A}))$$

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$$Pr_{\mathcal{P} \otimes \mathcal{A}}^{\max}(\langle s_0, q_0 \rangle \models Acc) = Pr_{\mathcal{P}}^{\max}(s_0 \models \mathcal{L}(\mathcal{A}))$$

Proof idea of “ \geq ”:

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MDP analysis with GFG

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Proof of “ \leq ” is rather technical

From LTL to GFG

- NBA to GFG nondet. parity automaton with at most $2^n \cdot n^{2n}$ states from Henzinger and Piterman, 2006

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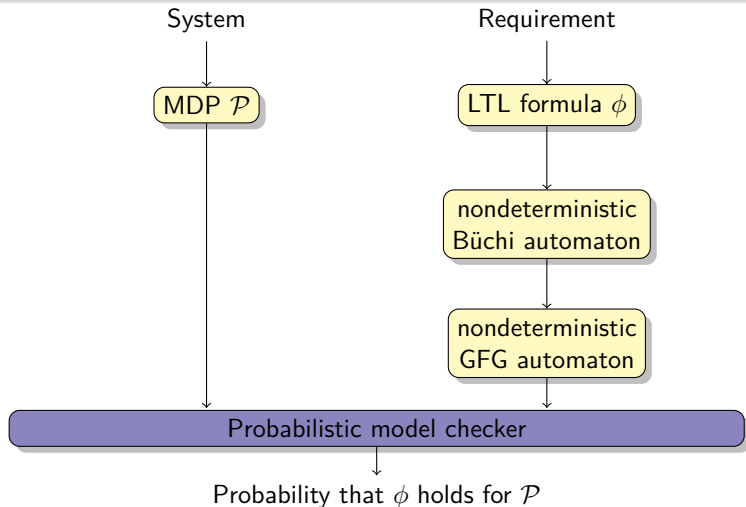
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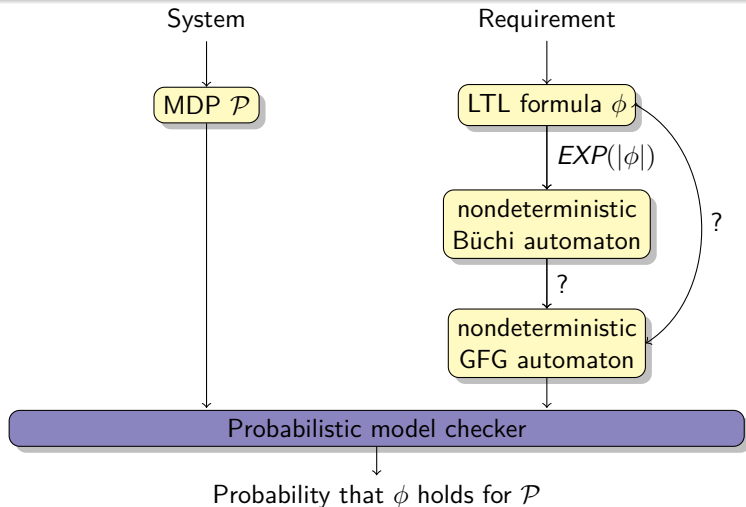
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- intended for symbolic implementation

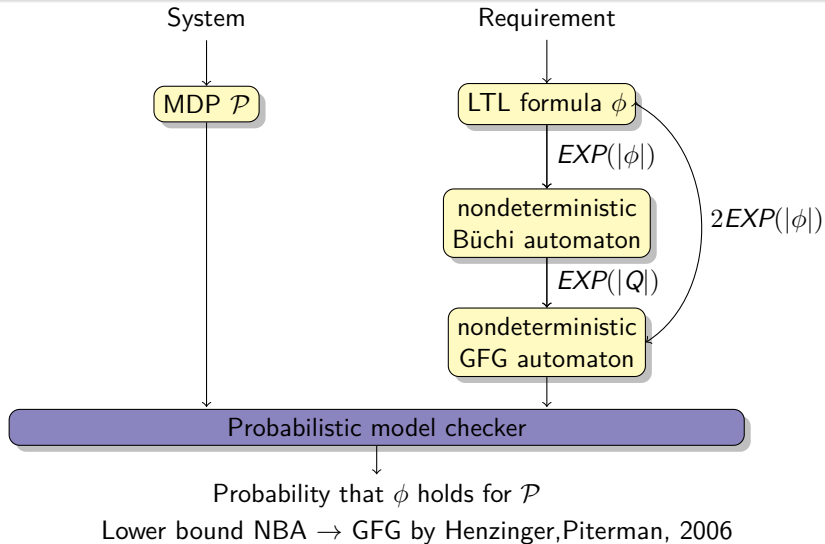
Probabilistic model checking



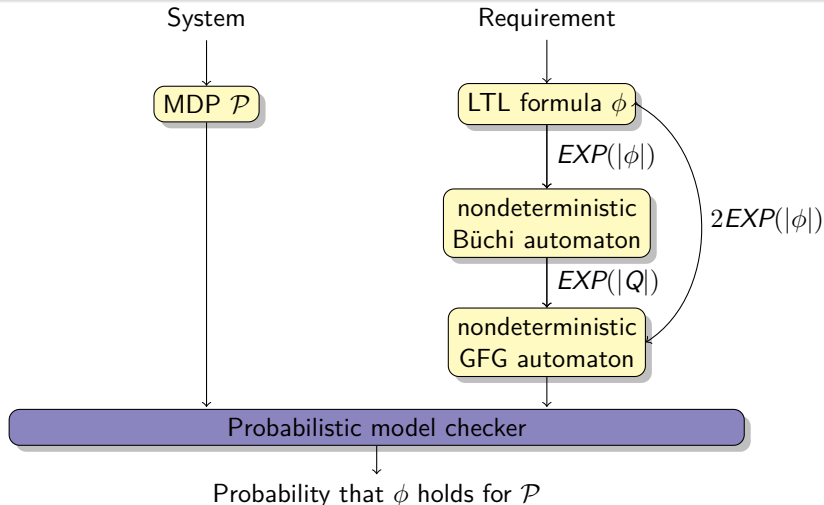
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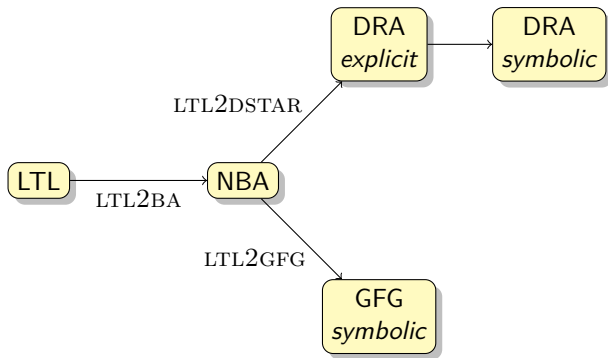
Probabilistic model checking



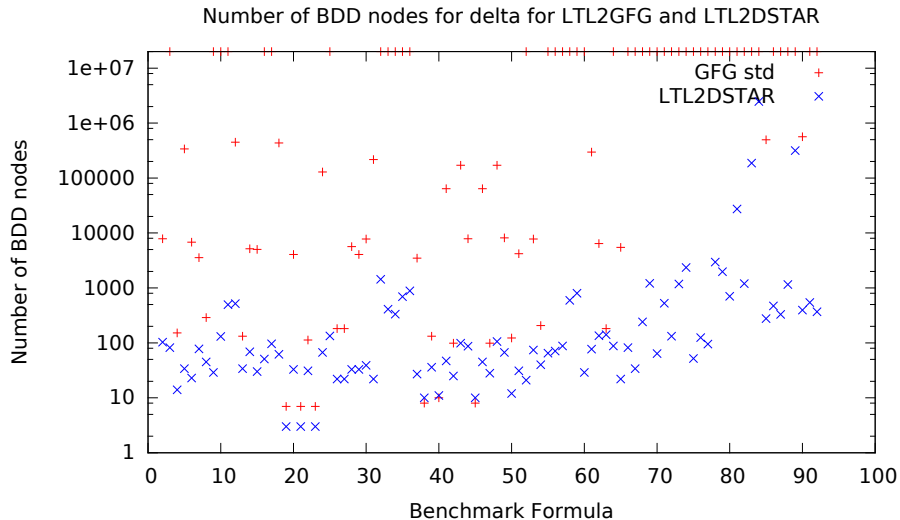
Lower bound NBA \rightarrow GFG by Henzinger, Piterman, 2006

Lower bound LTL \rightarrow GFG: straightforward adaption of
Kupferman, Rosenberg 2011

Implementations

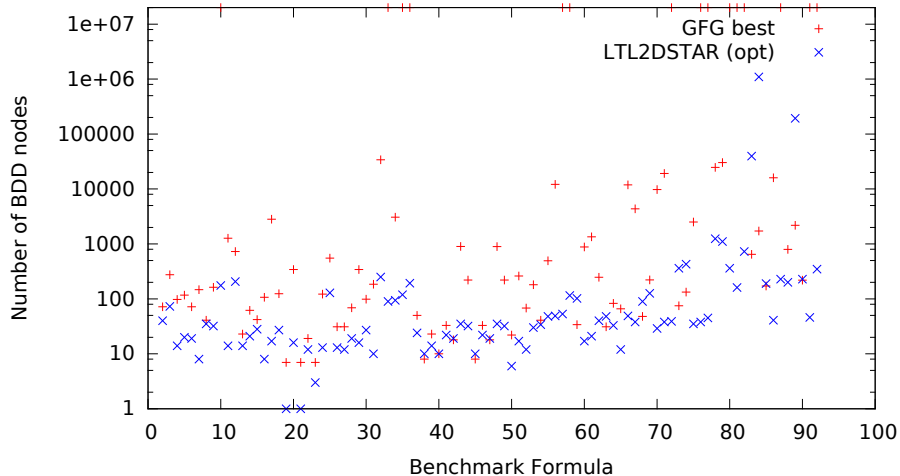


Size of symbolic BDD representation



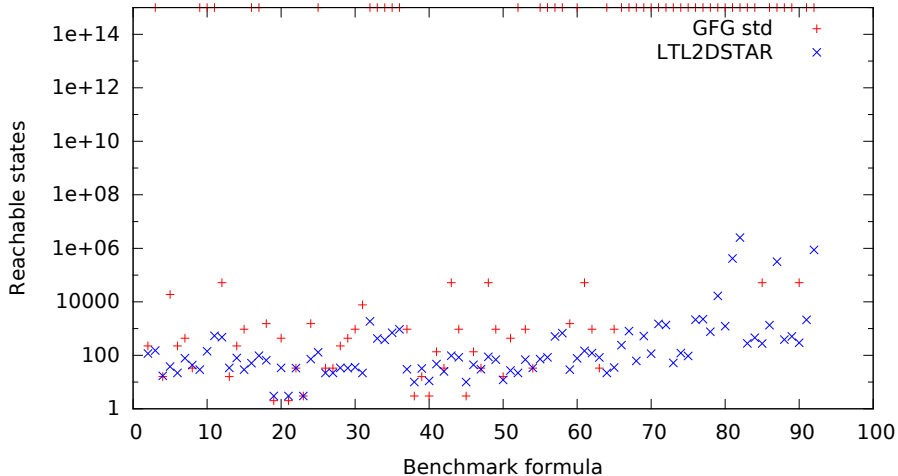
Size of symbolic BDD representation with heuristics

Number of BDD nodes for delta for LTL2GFG and LTL2DSTAR



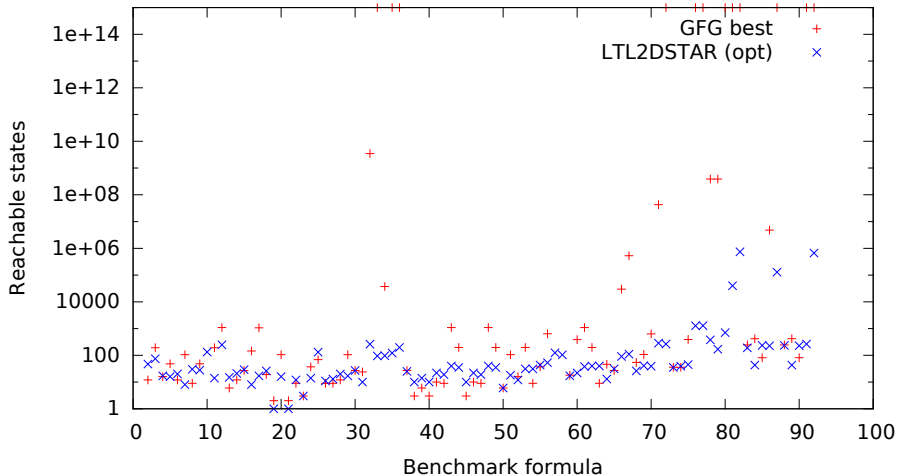
Reachable states

Reachable states for LTL2GFG and LTL2DSTAR

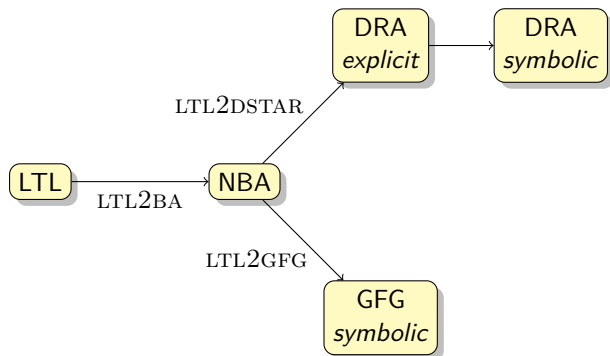


Reachable states with heuristics

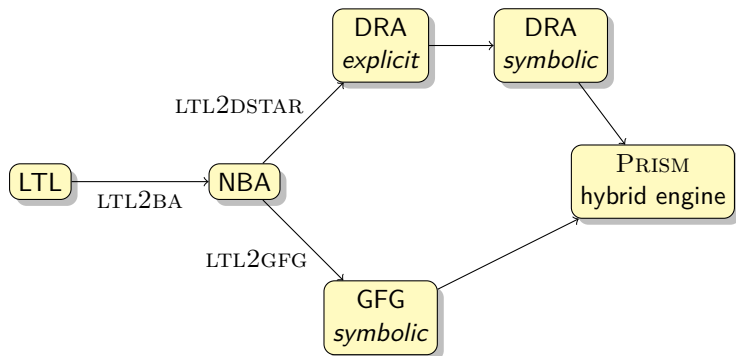
Reachable states for LTL2GFG and LTL2DSTAR



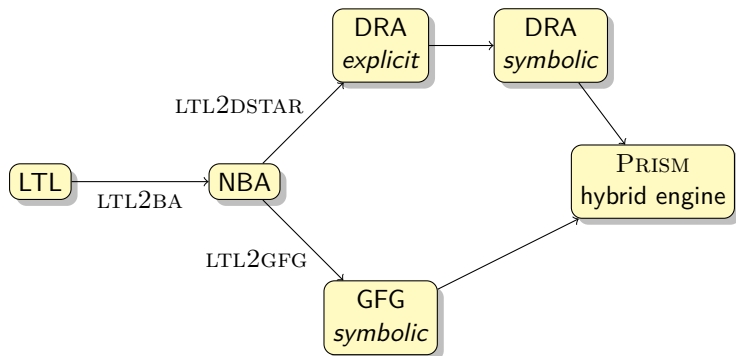
Implementation in probabilistic model checker PRISM



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Case study: parts of WiFi carrier-sense protocol of IEEE 802.11
(Kwiatkowska, Norman and Sproston, 2002)

Benchmark: IEEE 802.11

$\Pr_{\mathcal{P}}^{\min}(\varphi)$	time	
	LTL2GFG	PRISM std.
$\diamond \text{Done}$	23.4 s	5.7 s
$\neg \diamond \square \text{error handling}$	38.4 s	0.7 s
$(\square \diamond \text{Backoff}_1) \rightarrow (\square \diamond \text{vuln}_1)$	63.4 s	2.9 s
$\square(\text{colision} \rightarrow \diamond \text{msg_send}_1)$	43.6 s	3.1 s
$\diamond \text{Done} \wedge \square \# \text{collision} < 2$	97.6 s	42.9 s

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- Evaluation of the transformation from NBA to GFG and the model checking process in PRISM

Thank you for your attention!

Questions or remarks?